

Goal

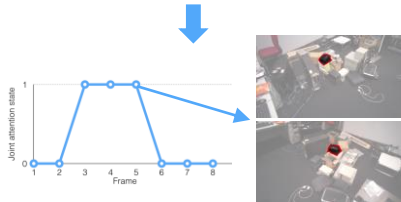
Discovering objects of joint attention using multiple first-person videos (FPVs) with points of gaze (PoG) data

Task

- Temporally localize time intervals of joint attention
- Spatially segment the object of joint attention



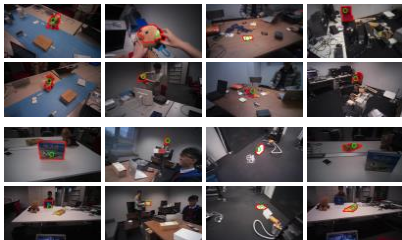
Input: multiple FPVs with PoG data



Output: Joint attention states and object segmentation

Dataset

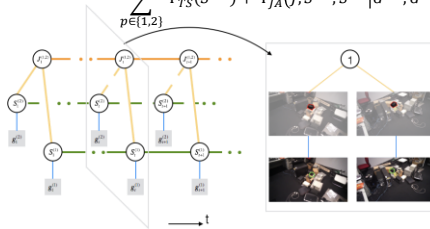
- 24 pairs of egocentric videos with gaze data (20 ~ 60 secs)
- 5 different environments, 20+ different objects
- Annotation of joint attention period & object segments



Problem Formulation

Given gaze position \mathbf{G} , we aim to infer joint attention state \mathbf{J} and segment the object of joint attention (\mathbf{S}), by minimizing the objective function:

$$\Psi(S^{(1)}, S^{(2)} | G^{(1)}, G^{(2)}) = \sum_{p \in \{1,2\}} \Psi_{GO}(S^{(p)} | G^{(p)}) + \sum_{p \in \{1,2\}} \Psi_{TS}(S^{(p)}) + \Psi_{JA}(J, S^{(1)}, S^{(2)} | G^{(1)}, G^{(2)}) + \Psi_{TJ}(J)$$



Gaze proximity and objectness

$$\Psi_{GO}(S^{(p)} | G^{(p)}) = \sum_{t=1}^T \left(\lambda_{G01} \frac{\|C(s_t^{(p)}) - \theta_t^{(p)}\|_2}{|s_t^{(p)}|^{1/2}} + \lambda_{G02} \left(1 - \frac{|s_t^{(p)}|}{|H(s_t^{(p)})|} \right) \right),$$

$C(s_t^{(p)})$: Centroid of segment $s_t^{(p)}$, $|H(s_t^{(p)})|$: Area of convex hull of $s_t^{(p)}$

Temporal consistency of segments

$$\Psi_{TS}(S^{(p)}) = \lambda_{TS} \sum_{t=1}^{T-1} (1 - f_{sim}(s_t^{(p)}, s_{t+1}^{(p)}))$$

f_{sim} : cosine similarity of features extracted from segments

Joint attentionnness

$$\Psi_{JA}(J, S^{(1)}, S^{(2)} | G^{(1)}, G^{(2)}) = \sum_{t=1}^T (\lambda_{JA1} Y(j_t, s_t^{(1)}, s_t^{(2)}, \mathbf{g}_t^{(1)}, \mathbf{g}_t^{(2)}) + \lambda_{JA2} Z(j_t))$$

Y measures visual similarity of segments:

$$Y(j_t, s_t^{(1)}, s_t^{(2)}, \mathbf{g}_t^{(1)}, \mathbf{g}_t^{(2)}) = j_t (1 - f_{sim}(s_t^{(1)}, s_t^{(2)})) + (1 - j_t) \alpha (\mathbf{g}_t^{(1)}, \mathbf{g}_t^{(2)})$$

α computes visual similarities around gaze region like [1]

$$Z(j_t) = \begin{cases} j_t, & \text{magnitude of global motion} > \delta_m \\ 0, & \text{otherwise} \end{cases}$$

Temporal consistency of joint attention

$$\Psi_{TJ}(J) = \lambda_{TJ} \sum_{t=1}^{T-1} |j_t - j_{t+1}|$$

[1] Kera et al. CVPRW2016

Experiment

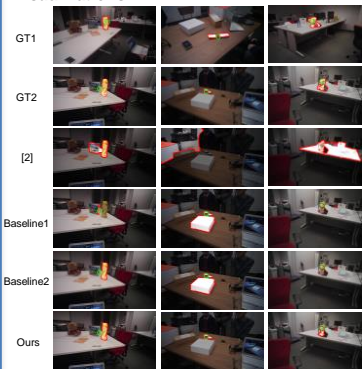
Spatial segmentation task

Method	FtF-large	FtF-small	SbS-large	SbS-small	Avg.
ObMiC [2]	0.287	0.212	0.065	0.336	0.225
Baseline1	0.552	0.599	0.681	0.691	0.631
Baseline2	0.611	0.629	0.723	0.726	0.672
Ours	0.633	0.660	0.730	0.735	0.690

Temporal localization task

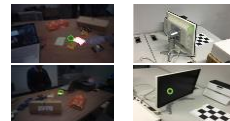
Method	FtF-large (%)	FtF-small (%)	SbS-large (%)	SbS-small (%)	Avg. (%)	F1 score			
Kera et al. [1]	74.5	89.7	69.7	93.8	72.9	96.5	67.1	83.4	79.0
Ours	91.9	92.8	84.7	86.5	94.3	92.6	79.7	98.7	89.3

Visualizations



- GT1,2: ground truth of person 1,2
- Baseline1: Ψ_{GO} only, Baseline2: $\Psi_{GO} + \Psi_{TS}$
- [2]: Fu et al. CVPR2014

Failure cases



- Different objects with similar appearance
- Same object with different appearances

Future work

- Use predicted gaze instead of eye tracker
- Use 3D geometric relation between FPVs